

**VERTICAL/INCLINED WHEELCHAIR LIFTS
RESIDENTIAL INSTALLATIONS
ASME 18.1b (2001) Sections 5 & 6; NFPA 70, 2002**

WCLR/WCLIR - _____

Site Name: _____ City: _____ Date: ____/____/____

VERTICAL & INCLINED WHEELCHAIR LIFTS	A18.1 Sect 5 & 6	COMMENTS	Pass
Runways (Vertical)	5.1	1) Runways a) Runway construction for lifts that penetrate a floor must comply with para. 2.1.1 and with the building code. b) Only lifts installed in conformance with para. 2.1.1 shall serve more than two landings.	<input type="checkbox"/> <input type="checkbox"/>
	5.1.1.1	2) Guarding a) The runway shall be guarded at the upper landing by a door at least 36 in. (914 mm) high of solid construction and provided with a combination mechanical lock and electric contact. b) The door shall be permitted to be opened only if the platform floor is within 2 in. (51 mm) of that landing. c) A smooth vertical fascia of unperforated construction shall be securely fastened from the upper landing sill to the level of the lower landing sill. i) It shall be equal to or stronger than 0.0598 in. (1.519 mm) sheet steel and guard the full width of the platform. ii) The fascia shall not be permanently deformed when a force of 125 lbf (556 N) is applied on any 4 in. (102 mm) by 4 in. (102 mm) area.	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>
	5.1.1.3	d) A metal guard at least 6 in. (152 mm) in height and extending the full width of the platform shall be installed on the lower landing side of the platform to prevent a wheelchair from rolling off the platform. i) The guard shall be automatically actuated by the movement of the platform away from the lower landing, and it shall remain in the elevated position until the platform returns to the lower landing.	<input type="checkbox"/> <input type="checkbox"/>
	5.1.1.4	e) The guard shall be operated with positive cam action or provided with an electric contact which shall stop the platform if the guard is not fully elevated when the platform has traveled 6 in. (152 mm) away from the lower landing.	<input type="checkbox"/>
	5.1.1.5	f) The guard shall withstand, without permanent deformation, a force of 125 lbf (556 N) applied on any 4 in. (102 mm) by 4 in. (102 mm) area. i) This force shall not cause the height of the ramp, at any point in its length, to be less than 6 in. (152 mm) measured vertically from the surface of the platform floor.	<input type="checkbox"/> <input type="checkbox"/>
	5.1.1.6	g) The sides of the platform not used for entrance or exit shall be guarded to a height of at least 36 in. (914 mm) by smooth construction with no openings, other than those necessary for the operation of the lift. i) Those openings necessary for operation shall reject a ball 1/2 in. (13 mm) in diameter.	<input type="checkbox"/> <input type="checkbox"/>
	5.1.1.7	h) The underside of the platform shall be equipped with a device which: i) If the platform is obstructed in its downward travel by a force not to exceed 4 lbf (17.8 N) applied anywhere on its underside; ii) will actuate a contact which shall cause electric power to be removed from the driving machine motor and brake; and iii) cause the platform to stop its downward motion within 2 in. (51 mm). iv) Motion shall be permitted to resume when the force is removed. v) When the installation conforms to the requirements of para. 2.1.1 or 2.1.2, the sensing device on the underside of the platform is not required.	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>
	5.1.1.8	i) The platform floor-to-sill clearance at the upper landing shall not exceed 3/4 in. (19 mm).	<input type="checkbox"/>

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Runways (Inclined)	6.1.1	1) Free Passage Width. a) A free passage width of not less than 20 in. (508 mm) shall be provided. b) If the platform can be folded when not in use, the distance will be measured from the folded position.	N/A <input type="checkbox"/> <input type="checkbox"/>	
	6.1.2	2) Clearances. a) Clearances between the platform and adjacent surfaces shall not be less than 3/4 in. (19 mm). b) At no point in its travel shall the edge of the platform facing the upper landing be more than 24 in. (610 mm) above a step or landing as measured vertically.	<input type="checkbox"/> <input type="checkbox"/>	
	6.1.3	3) Pits and Ramps. a) A pit, floor-mounted ramp, or retractable platform-mounted ramp shall be provided. b) Retractable ramps shall conform to the requirements of para. 6.6.6. Where a pit is provided, it shall be protected as required by the authority having jurisdiction.	<input type="checkbox"/> <input type="checkbox"/>	
Lower Access Ramp	5.1.3	1) A retractable ramp shall be permitted to be mounted on the platform. 2) When in use, the incline of the ramp shall not be greater than: a) 1 in 6, for heights up to 2½ in. (64 mm); b) 1 in 8, for heights greater than 2½ in. (64 mm) and less than 3 in. (76 mm); c) 1 in 12, for heights 3 in. (76 mm) or greater. d) The ramp shall extend the full width of the platform floor. e) It shall be permitted to be actuated by the movement of the platform away from the lower landing; and f) Shall remain retracted while the platform is away from the lower landing. g) The ramp shall be permitted to also be used as the guard specified in para. 5.1.1.3. 3) The ramp shall be operated by a positive mechanical action or shall be provided with an electric contact which will stop the movement of the platform within 6 in. (152 mm) of the lower landing if the ramp has failed to rise to its elevated position.	N/A <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>	
Structural Support	5.1.5	6.1.5	The structure on which the equipment is installed shall be capable of safely supporting the loads imposed.	<input type="checkbox"/>
Headroom Clearance	5.1.6	Headroom clearance throughout the range of travel shall be not less than 80 in. (2032 mm) as measured vertically from the platform floor.	<input type="checkbox"/>	

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Driving Means and Sheaves (Sections 5.3 & 6.3)	5.3	6.3	1) The driving means shall be one of the following: a) winding drum b) traction c) roped sprocket d) chain sprocket e) screw f) rack and pinion g) direct-plunger hydraulic h) roped-hydraulic i) lever hydraulic j) friction 2) Driving means utilizing a combination of two or more means shall conform to all applicable requirements of the respective means unless stated otherwise.	<input type="checkbox"/> <input type="checkbox"/>
	5.3.1.3	6.3.1.3	3) Friction gearing, clutch mechanisms, or couplings shall not be used to connect a driving machine drum or sheave to the main driving mechanism.	<input type="checkbox"/>
	5.3.1.4	6.3.1.4	4) Worm gearing having cast iron teeth shall not be used on the driving machine.	<input type="checkbox"/>
	Driving-Machine Brakes	5.4.1	6.4.1	1) Driving machines, except hydraulic, shall be equipped with friction brakes directly attached to the driving means through a continuous shaft, mechanical coupling, or toothed gearing applied by springs, or by gravity, and released electrically.
5.4.2			2) A single ground or short circuit, a counter-voltage or a motor-field discharge shall not prevent the brake magnet from allowing the brake to set when the operating device is placed in the stop position.	<input type="checkbox"/>
5.4.3		6.4.2	3) A machine brake is not required if a self-locking drive utilizing a lead screw, worm, or other positive gearing which will stop and hold the platform with the rated load within 4 in. (102 mm) of down travel after the power is removed is provided.	<input type="checkbox"/>
Friction Machines	8.3.1		1) The friction developed shall be self-adjusting to allow for wear and be capable of lifting and supporting a platform loaded with 125% of the rated load.	<input type="checkbox"/>
	8.3.2		2) The friction drive wheels shall be made of metal or other durable material or a combination of materials.	<input type="checkbox"/>
	8.3.3		3) Friction drive, if used to drive the over-speed governor, shall be independent of the main friction drive.	<input type="checkbox"/>
	8.3.4		4) If the over-speed governor is friction driven: a) the control system shall include circuitry to continually monitor the rotation of the over-speed governor driving means during travel. b) If rotation ceases, electric power shall be removed from the driving machine motor and brake (if provided) within 10 sec or 40 ft (1016 mm) of travel, whichever occurs first. c) Releasing operating controls shall be permitted to reset the monitor or its circuitry.	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>
	8.3.5		5) The force transmitted to the rotating device by friction shall be at least twice the force necessary to actuate the safeties.	<input type="checkbox"/>

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Screw Drive Machines	8.2.1		1) The screw machine shall function to raise or lower the platform acting in conjunction with a screw column which directly supports the platform.	<input type="checkbox"/>
	8.2.2		2) Screws shall be made of steel. Nuts shall be made of bronze or other materials having an elongation of at least 14% in 2 in. (51 mm).	<input type="checkbox"/>
	8.2.3		3) Means shall be provided to maintain the screw in its operating position under all conditions of operation. a) Screws suspended from their upper end shall be restrained at their lower end.	<input type="checkbox"/>
	8.2.6		4) Means shall be provided to prevent the disengagement of the nut from the screw column. a) This means shall be so designed and constructed as to prevent disengagement in the event of overtravel at full speed and without damage to any part of the lift installation.	<input type="checkbox"/>
	8.2.9		5) A positive mechanical means shall be provided to prevent rotation or separation of sections of a multiple section screw column.	<input type="checkbox"/>
	8.2.10		6) Means shall be provided to permit authorized personnel from a position outside the platform to raise or lower the platform manually in the event of a power failure, unless standby (emergency) power is provided.	<input type="checkbox"/>
Indirect-Drive Machines	5.3.9	6.3.6	1) Indirect-drive machines, utilizing V-belt drives, tooth drive belts, or drive chains, shall conform to the following requirements: a) requirements of para. 5.3.9.2 shall be permitted to be omitted if a self-locking drive meeting the requirements of para. 5.4.3 is provided. b) If multiple belts or chains are provided, they shall be preloaded and matched for length in sets.	N/A <input type="checkbox"/>
	5.3.9.1	6.3.6.1	2) Belts and Chains: a) Belt sets shall be selected on the basis of the manufacturer's rated breaking strength and a factor of safety of 10. b) Chain and sprocket sets shall be selected on the basis of recommendations set forth in the Supplementary Information section of ANSI/ASME B29.1, using a service factor of 2. c) Offset links in chain are not permitted. d) Sprockets in a chain drive set and also a driven set shall be assembled onto a common hub, with teeth cut in-line after assembly to assure equal load distribution on all chains. e) Tooth sheaves for a belt drive shall be constructed in a manner to assure equal load distribution on each belt in the set. f) Load determination for both the belt and chain sets shall be based on the maximum static loading on the platform, which is the full load in the platform at rest and at a position in the runway which creates the greatest load, including either the platform or counterweight resting on its buffer. g) Chain drives and belt drives shall be guarded to protect against accidental contact and to prevent foreign objects from interfering with drives.	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>
	5.3.9.2	6.3.6.2	3) Monitoring and Brake Location. a) Each belt or chain in a set shall be continuously monitored by a broken belt or chain device which shall function to automatically interrupt power to the machine and apply the brake in the event any belt or chain in the set breaks or becomes excessively slack. b) The driving machine brake shall be located on the traction sheave or drum assembly side of the driving machine so as to be fully effective in the event the entire belt set or chain set should break.	<input type="checkbox"/> <input type="checkbox"/>
	5.3.9.3		4) Replacement of Belts or Chains. a) If one belt or chain of a set is worn, stretched, or damaged so as to require replacement, the entire set shall be replaced. b) Sprockets and toothed sheaves shall also be replaced if worn.	<input type="checkbox"/> <input type="checkbox"/>
				<input type="checkbox"/>
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Fastening of Rope Suspension Means to Platform.	5.5.7	6.5.7	1) The platform ends of wire ropes shall be fastened in a return loop by properly made individual tapered babbitted sockets or properly attached fittings as recommended by wire rope manufacturers. 2) Clips of the U-bolt type shall not be used. 3) Tapered babbitted rope sockets and the method of babbitting shall conform to the requirements of para. 9.8.	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>
Guarding	5.5.8	6.5.8	1) All suspension means shall be guarded against accidental contact. 2) Suspension means which operate within a guide or track and travel at the same speed and in the same direction as the platform shall be considered suitably guarded.	<input type="checkbox"/> <input type="checkbox"/>
Platforms	5.6.1	6.6.1	1) Frame and Floor a) The frame shall be of metal construction and have a factor of safety of not less than 5 based on the rated load. b) The floor shall be of metal or wood construction with a nonskid surface.	<input type="checkbox"/> <input type="checkbox"/>
	5.6.2	6.6.1.1	2) Securing of Enclosures a) The enclosure shall be securely fastened to the floor and so supported that it cannot loosen or become displaced in ordinary service, on the application of the platform safety, or on buffer engagement. b) The platform enclosure shall be so constructed that removable portions cannot be dismantled from within the platform. c) Enclosure linings, decorative panels, light fixtures, and other apparatus or equipment attached to the enclosure shall be securely fastened and so supported that they will not loosen or become displaced in ordinary service, on platform safety application, or on buffer engagement. d) Panels attached to the enclosure for decorative or other purposes shall not be unfastened from inside the platform by the use of common tools or shall be permitted to be removed from inside the platform when perforations, exceeding that which would reject a ball 1/2 in. (13 mm) in diameter, in the enclosure used for panel hanging or support have permanent means to prevent straight through passage beyond the running clearance.	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>
	5.6.3	6.6.1.2	3) Strength and Deflection of Enclosure Walls. a) The enclosure walls shall be designed and installed to withstand a force of 75 lbf (334 N) applied horizontally at any point on the walls of the enclosure without permanent deformation nor cause the deflection to exceed 1 in. (25 mm).	<input type="checkbox"/>
	5.6.4		4) Use of Cast Iron. a) Cast iron shall not be used in the construction of any load bearing member of the platform frame or floor other than for guide shoes and guide shoe brackets.	<input type="checkbox"/>
	5.6.5		5) Floor Size (vertical). a) The inside net floor area shall not exceed 18 ft ² (1.67 m ²).	<input type="checkbox"/>
		6.6.2	6) Floor Area (inclined) a) The inside net floor area shall not exceed 12 ft ² (1.11 m ²).	<input type="checkbox"/>
	5.6.6		7) Illumination. a) The minimum illumination at the landing edge of the floor with the landing door open shall be not less than 5 ftc (54 lx).	<input type="checkbox"/>

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Terminal Stopping Devices	5.9.1	6.9.1	1) Normal terminal stopping devices shall be permitted to use mechanically operated, magnetically operated, optical, or static type switches. a) Final terminal stopping devices shall use only mechanically operated switches for determining platform position. b) Terminal stopping devices which are located on the platform or in the runway shall be of the enclosed type and securely mounted in such a manner so that horizontal movement of the platform shall not effect the operation of the device.	<input type="checkbox"/>
		6.9.2	2) Normal stopping devices operated by the platform shall be provided, and shall be set to stop the platform floor within a tolerance of 1/2 in. (13 mm) of the landings under rated loading to zero loading conditions. a) The normal stopping devices shall be permitted to also serve as the upper and lower normal terminal stopping devices.	<input type="checkbox"/>
	5.9.3	6.9.3	3) Upper and lower final terminal stopping devices operated by the platform shall be provided to remove power from the motor and the brake, if provided, except as specified in para. 5.9.6. a) They shall be set to stop the platform after it travels past the normal terminal stopping device and before striking an obstruction. b) A slack-rope device equipped with a slack-rope switch of the enclosed manually reset type, which shall cause the electric power to be removed from the driving machine motor and brake if any hoisting rope becomes slack shall be permitted to be used as the lower final terminal stopping device.	<input type="checkbox"/>
		6.9.4	4) Final terminal stopping devices shall be mechanically operated. a) The switch contacts shall be directly opened mechanically. b) Arrangements which depend on a spring or gravity, or a combination thereof, to open the contacts shall not be used.	<input type="checkbox"/>
	5.9.5	6.9.5	5) The final terminal stopping device shall not control the same controller switches as the normal terminal stopping devices unless two or more separate and independent switches are provided, two of which shall be closed to complete the driving-machine motor and brake circuit in either direction of travel. a) Where a two or three-phase alternating-current driving-machine motor is used, these switches shall be of the multipole type. b) The control shall be so designed and installed that a single ground or short circuit shall be permitted to allow either, but not prevent both, the normal and final stopping device circuits from stopping the platform.	<input type="checkbox"/>
	5.9.6	6.9.6	6) Final terminal stopping devices are not required for direct-plunger hydraulic driving machines. a) Lower final terminal stopping devices are not required where the limitations of the machine or runway limit the travel of the platform (e.g., a platform at rest on the bottom terminal landing).	<input type="checkbox"/>
Operation	5.10.1	6.10.1	1) Operation of the chairlift from the upper or lower landing and from the chair shall be controlled by "UP" and "DOWN" control switches at all stations, and shall be by means of the continuous pressure type. 2) Controls shall be 48 in. (1220 mm) max. and 15 in. (380 mm) min. above the platform floor or facility floor or ground level. 3) Operating devices shall be designed so that both the "UP" and "DOWN" circuits cannot be operated at the same time.	<input type="checkbox"/>

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Attendant Operation	5.10.2	6.10.2	1) Attendant operation shall be permitted to be provided. 2) Where provided, it shall conform to the following requirements. a) The attendant shall operate the lift by means of a continuous-pressure switch located on a control box on the free end of a detachable, flexible cord not more than 5 ft (1524 mm) in length. b) A manually reset emergency stop switch shall also be provided in the control box. c) No controls, other than an emergency stop switch, shall be provided on the lift. d) Where the equipment operates on a straight flight of stairs, and where the platform is within sight during its entire travel, provisions shall be permitted to be made for the attendant to operate the lift from the top or bottom of the stairs.	N/A <input type="checkbox"/>
	5.10.2.1	6.10.2.1		<input type="checkbox"/>
	5.10.2.2	6.10.2.2		<input type="checkbox"/>
	N/A	6.10.2.3		<input type="checkbox"/>
Motor Reversal Protection.	5.10.4	6.10.4	1) Where a non- instantaneous reversible motor is used, a protective circuit or device shall be provided to prevent the motor from continuing in the same direction if the reversing control is activated.	<input type="checkbox"/>
Phase Reversal and Failure Protection	5.10.5	6.10.5	1) Lifts having polyphase alternating current power supply shall be provided with means to prevent the starting of the lift motor if the phase rotation is in the wrong direction, or if there is a failure of any phase. 2) This protection shall be considered to be provided if a reversal of phase of the incoming polyphase alternating current power will not cause the driving machine motor to operate in the wrong direction.	<input type="checkbox"/> <input type="checkbox"/>
Emergency Stop Switch	5.10.6	6.10.8	1) An emergency stop switch shall be provided in the platform. 2) Located in or adjacent to each platform operating panel. 3) When opened, this switch shall cause the electric power to be removed from the driving-machine motor and brake. 4) Emergency stop switches shall be of the manually opened and closed type and have red operating handles or buttons. 5) They shall be conspicuously and permanently marked "STOP" and shall indicate the "STOP" and "RUN" positions. 6) Switches shall be positively opened mechanically and their opening shall not be solely dependent on springs.	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>
Slack-Rope and Slack-Chain Devices for Winding Drum and Roller-Chain-Type Driving Machines.	5.10.7	6.10.7	1) Winding drum driving machines with rope suspension shall be provided with a slack-rope device of the manually reset type that will remove power from the motor and brake if the platform is obstructed in its descent and the suspension ropes slacken. 2) Lifts with roller chain suspension means shall be provided with a slack-chain device which will remove power from the motor and brake if the platform is obstructed in its descent and the suspension means slacken. 3) This device is not required to be of the manually reset type if the chain sprockets are guarded to prevent the chain from becoming disengaged from the sprockets.	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>
Release and Application of Driving-Machine Brake.	5.10.8	6.10.9	1) Driving-machine brakes shall not be electronically released until power has been applied to the driving-machine motor. 2) All power feed lines to the brake shall be opened and the brake shall apply automatically when any operating device in para. 5.10.1 or 5.10.2 is in the "STOP" position and when any electrical protective device functions.	<input type="checkbox"/> <input type="checkbox"/>
Manual Operation <i>(vertical only)</i>	5.10.10		1) Means shall be provided to permit authorized personnel from a position outside the platform to raise or lower the platform manually in the event of power failure, unless standby (emergency) power is provided.	<input type="checkbox"/>

